

$$1. \quad B = \begin{pmatrix} \frac{3}{4} & \frac{1}{4} & -\frac{1}{4} \\ -\frac{1}{4} & \frac{1}{4} & \frac{3}{4} \\ \frac{1}{4} & -\frac{1}{4} & \frac{1}{4} \end{pmatrix} \quad A+C = \begin{pmatrix} 4 & 1 & 0 \\ 0 & 2 & 1 \\ 1 & 0 & 2 \end{pmatrix}$$

$$AB = BA = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = I_3 \quad |A| = 4$$

$$|AB| = 1 \quad |BA| = 1$$

$$A^{-1} = \begin{pmatrix} \frac{3}{4} & \frac{1}{4} & -\frac{1}{4} \\ -\frac{1}{4} & \frac{1}{4} & \frac{3}{4} \\ \frac{1}{4} & -\frac{1}{4} & \frac{1}{4} \end{pmatrix} \quad A^{-1}A = AA^{-1} = I_3$$

$$2. \quad 1) \quad \text{solution } \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \quad \left( \begin{array}{ccc|c} 1 & 0 & 1 & 2 \\ 2 & -3 & 5 & 4 \\ 3 & 2 & -1 & 4 \end{array} \right) \rightarrow \left( \begin{array}{ccc|c} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \end{array} \right) \text{ RREF}$$

$$2) \quad \text{No solution} \quad \left( \begin{array}{ccc|c} 1 & 2 & 1 & 2 \\ 2 & -4 & -3 & 0 \\ -1 & 6 & -4 & 2 \\ 1 & -1 & 0 & 4 \end{array} \right) \rightarrow \left( \begin{array}{ccc|c} 1 & -1 & 0 & 4 \\ 0 & 3 & 1 & -2 \\ 0 & 0 & 1 & 4 \\ 0 & 0 & 0 & 40 \end{array} \right) \text{ You may get different matrices here, but the conclusion is the same!}$$

$$3) \quad \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = x_3 \begin{pmatrix} -2 \\ -1 \\ 1 \\ 0 \end{pmatrix} + x_4 \begin{pmatrix} 4 \\ 3 \\ 0 \\ 1 \end{pmatrix} + \begin{pmatrix} 1 \\ 2 \\ 0 \\ 0 \end{pmatrix} \quad \left( \begin{array}{ccc|c} 1 & 0 & 2 & -4 \\ 0 & 1 & 1 & -3 \end{array} \right)$$

where  $x_3, x_4$  are parameters

3. I will show  $V$  is a subspace of  $C^1(\mathbb{R})$ , and leave  $W$  is a subspace of  $C^1(\mathbb{R})$  as an exercise.

First of all,  $V$  is a subset of  $C^1(\mathbb{R})$ . Assume  $C^1(\mathbb{R})$  is a vector space. We then only need to check the closure properties.

①

i) Closure under addition

For every  $x(t), y(t) \in V$ , we have

$$x(t) \in C^1(\mathbb{R})$$

$$y(t) \in C^1(\mathbb{R})$$

$$x(1) = 0$$

$$y(1) = 0$$

Since  $C^1(\mathbb{R})$  is a vector space, it is closed under addition, then

$$\boxed{x(t) + y(t) \in C^1(\mathbb{R})}$$

$$\boxed{(x+y)(1) = x(1) + y(1) = 0 + 0 = 0}$$

Then we get  $x(t) + y(t) \in V$

ii) Closure under scalar multiplication

For every  $y(t) \in V$ ,  $k \in \mathbb{R}$ , we have

$$y(t) \in C^1(\mathbb{R})$$

Since  $C^1(\mathbb{R})$  is a vector space, it is closed under scalar multiplication, then

$$\boxed{ky(t) \in C^1(\mathbb{R})}$$

$$y(1) = 0$$

$$\boxed{(ky)(1) = ky(1) = 0}$$

Then we get  $ky \in V$  #

4. In order to show  $S$  forms a basis of  $\mathbb{R}^3$ , we need to check the following two conditions

i)  ~~$\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$~~  are linearly independent

$$\text{Assume } a \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + b \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} + c \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

Solving this linear system, we get  $a = b = c = 0$ , which means they are linearly independent.

ii)  $\text{span} \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \right\} = \mathbb{R}^3$

In order to show the above equality, we need to check

$$\mathbb{R}^3 \subseteq \text{span} \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \right\} \subseteq \mathbb{R}^3$$

②

$\text{span} \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \right\} \subseteq \mathbb{R}^3$  is trivial because

$\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \in \mathbb{R}^3$ , their linear combination must belong to  $\mathbb{R}^3$

On the other hand, show  $\mathbb{R}^3 \subseteq \text{span} \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \right\}$

For every  $\begin{pmatrix} x \\ y \\ z \end{pmatrix} \in \mathbb{R}^3$ , we assume  $\begin{pmatrix} x \\ y \\ z \end{pmatrix}$  can be expressed by linear combination of  $\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$ , which is

$$a \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + b \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} + c \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

From the above linear system, we get  $a = x - y$   
 $b = y - z$   
 $c = z$

which means every vector in  $\mathbb{R}^3$  can be expressed by the linear combination of  $\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$

i.e.,  $\mathbb{R}^3 \subseteq \text{span} \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \right\}$  #

Chap 1 & 2

1.  $\frac{dy}{dt} = ky(1-y)$

This is an autonomous differential equation. can be solved by separation of variables

$$\frac{dy}{dt} = ky(1-y)$$

i) equilibrium solutions  $y \neq 0, y(t) \equiv 1$

ii) If  $y(1-y) \neq 0, \frac{dy}{y(1-y)} = k dt$  partial fractions decomposition

$$\frac{1}{y} dy + \frac{1}{1-y} dy = k dt$$

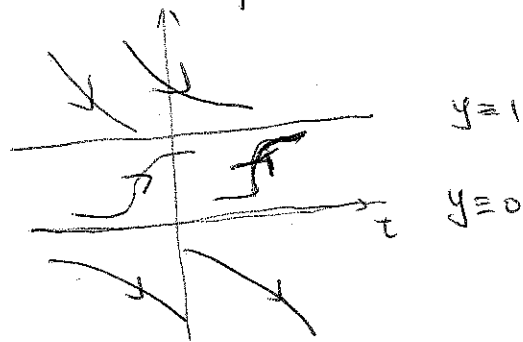
$$\ln|y| - \ln|1-y| = kt + C$$

(3)

If  $0 < y < 1$   $y(t) = \frac{e^{kt} \cdot e^c}{1 + e^{kt} \cdot e^c}$   $c \in \mathbb{R}$

If  $y$  belongs to  $(1, +\infty)$  or  $(-\infty, 0)$ , exercise!

Direction fields



$$\frac{dy}{dt} \begin{cases} - & y > 1 \\ + & 0 < y < 1 \\ - & y < 0 \end{cases}$$

stability:  $y=1 \Rightarrow$  stable (sink)

$y=0 \Leftrightarrow$  unstable (source)

2.  $y' = -\frac{1+y^2}{1+t^2}$  separation of variables  $\rightarrow \frac{dy}{1+y^2} = -\frac{dt}{1+t^2}$

$\rightarrow \arctan y = -\arctan t + C$   $C \in \mathbb{R}$

$\rightarrow y = \tan(-\arctan t + C)$   $y(0) = -1 \rightarrow C = -\frac{\pi}{4}$

$\rightarrow y = \tan(-\arctan t - \frac{\pi}{4})$

$3y^2 y' - 2y^3 - t - 1 = 0$  substitution  $z = y^3$

$\rightarrow z' - 2z = t + 1$  Integrating Factor  $e^{-2t}$

$\rightarrow z = -\frac{3}{4} - \frac{t}{2} + C e^{2t}$   $y(0) = 2 \rightarrow z(0) = 8 \rightarrow C = \frac{35}{4}$

$\rightarrow y(t) = \left(-\frac{3}{4} - \frac{t}{2} + \frac{35}{4} e^{2t}\right)^{\frac{1}{3}}$

$y' = t^2 \exp(y + 2t)$  separation of variables  $y(t) = -\ln\left(-\frac{1}{2}t^2 e^{2t} + \frac{1}{2}t e^{2t} - \frac{1}{4}e^{2t} + C\right)$   $C \in \mathbb{R}$

$y' - y = \exp(3t)$  Integrating factor  $e^{-t} \rightarrow y(t) = \frac{1}{2} e^{3t} + C e^t$   $C \in \mathbb{R}$

$y' = 1 - y^2$  separation of variables  $y = \pm 1$  equilibria

partial fractions decomposition  $-1 < y < 1$   $y(t) = \frac{e^{t^2} e^c - 1}{e^t e^c + 1}$   $C \in \mathbb{R}$

$y > 1$  or  $y < -1$  exercise

$y' = y(a - b \ln y)$   $y > 0$  substitution  $z = \ln y \rightarrow z' = a - bz$

Integrating factor  $e^{bt} \rightarrow y(t) = e^{\frac{a}{b}} e^{ce^{-bt}}$   $C \in \mathbb{R}$

(4)